

Data Driven Computational Imaging Survey

Tristan Swedish
CVPR Tutorial



Data-Driven Computational Imaging

Time	Title	Presenter
08:30 - 08:50	Introduction to Computational Imaging	Guy Satat (MIT)
08:50 - 09:15	Data-Driven Computational Imaging Survey	Tristan Swedish (MIT)
09:15 - 10:00	Data-Driven Non-line-of-sight Imaging and 3D Reconstruction	Guy Satat (MIT)
10:00 - 10:20	Break	
10:20 - 11:00	Rendering and Simulation for Data-Driven Computational Imaging	Tristan Swedish (MIT)
11:00 - 12:00	Visual Sensing Using Machine Learning	Vivek Boominathan (Rice), Ashok Veeraraghavan (Rice)

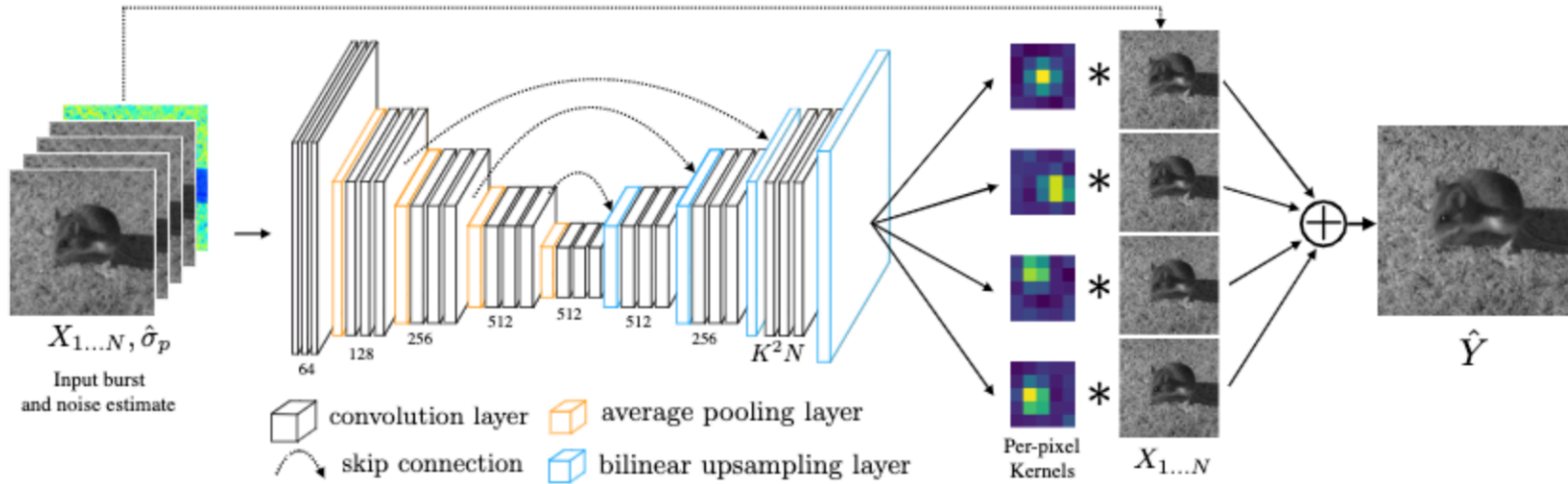
Overview

Computational Imaging is Diverse:

- Low-level Processing (Denoising and Demosaicking)
- 3D Imaging
- Lensless, Speckle, Scattering
- Non-line-of-sight
- Imaging System Design
- Tomography and Deconvolution
- Microscopy

Low Level Processing (de-noising, de-mosaicking)

Burst Denoising with Kernel Prediction Networks



Noise2Noise

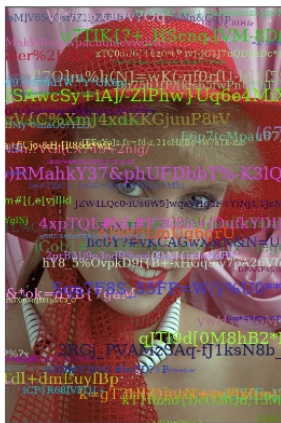
$p = 0.22$ $p = 0.81$



$p \approx 0.04$ $p \approx 0.42$



Example training pairs



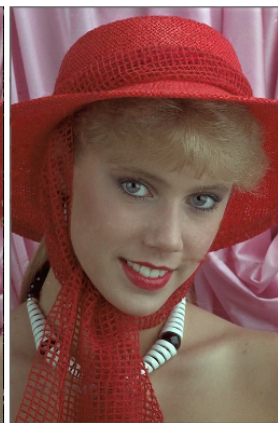
Input ($p \approx 0.25$)
17.12 dB



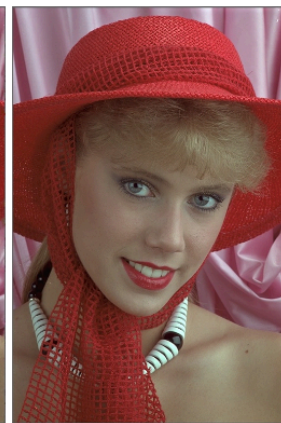
L_2
26.89 dB



L_1
35.75 dB



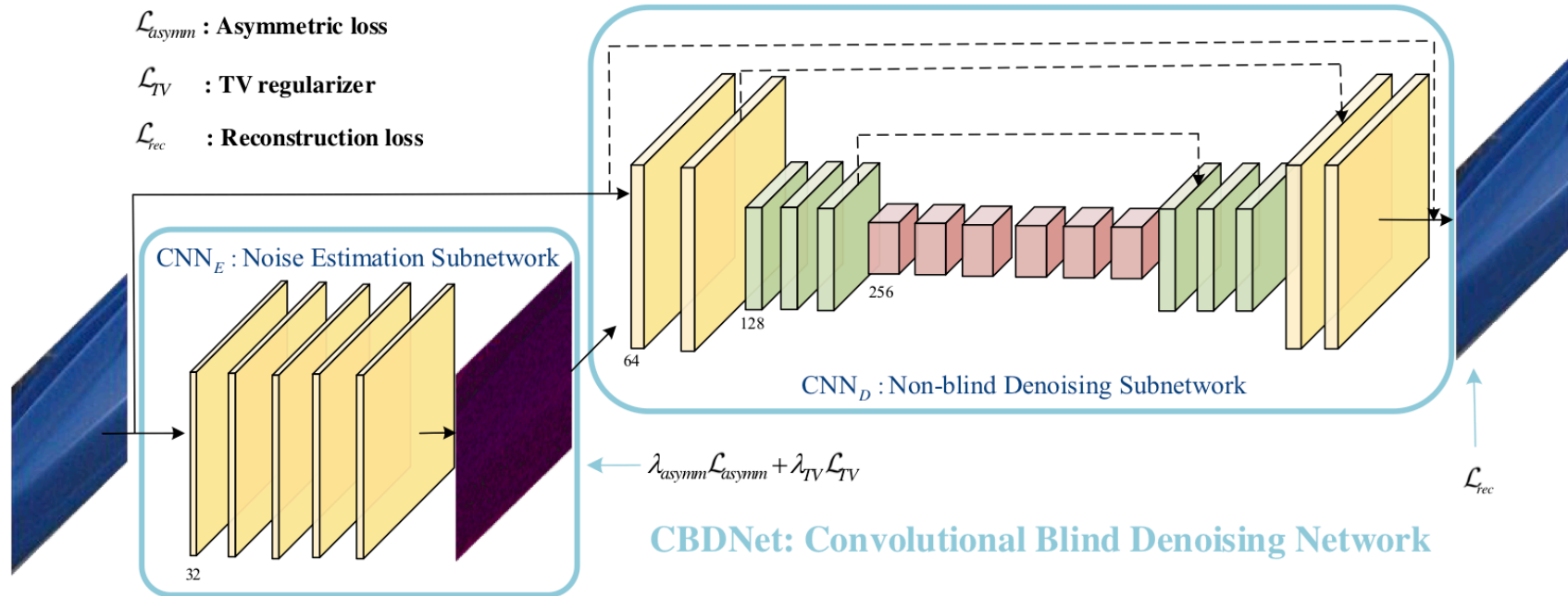
Clean targets
35.82 dB



Ground truth
PSNR

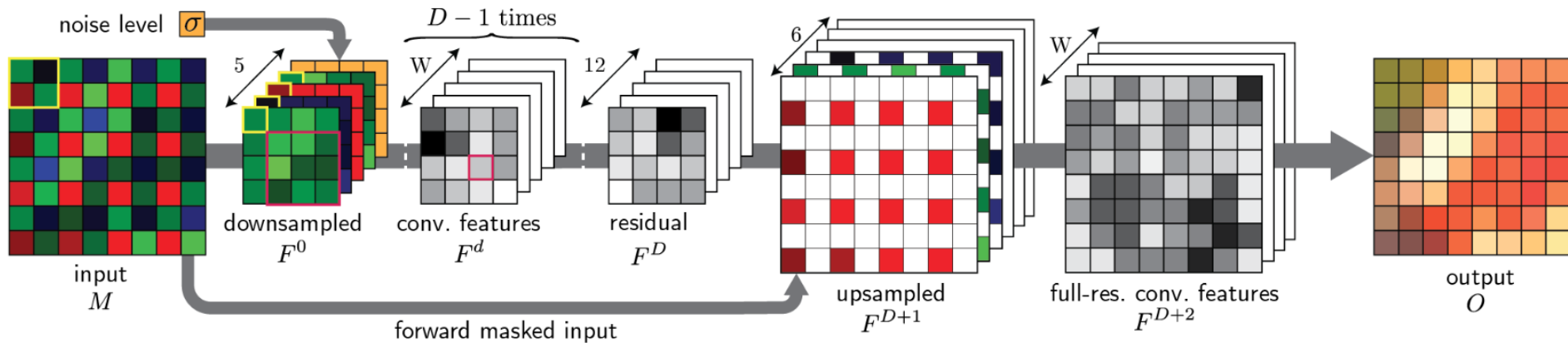
Jaakko Lehtinen, Jacob Munkberg, Jon Hasselgren, Samuli Laine, Tero Karras, Miika Aittala, Timo Aila. *Noise2Noise: Learning Image Restoration without Clean Data*. ICML, 2018.

Toward Convolutional Blind Denoising of Real Photographs



S. Guo, Z. Yan, K. Zhang, W. Zuo and L. Zhang. *Towards Convolutional Blind Denoising of Real Photographs*. CVPR, 2019.

Deep Joint Demosaicking and Denoising



Michaël Gharbi, Gaurav Chaurasia, Sylvain Paris, Frédo Durand. *Deep joint demosaicking and denoising*. Trans. on Graphics (TOG), 2016.

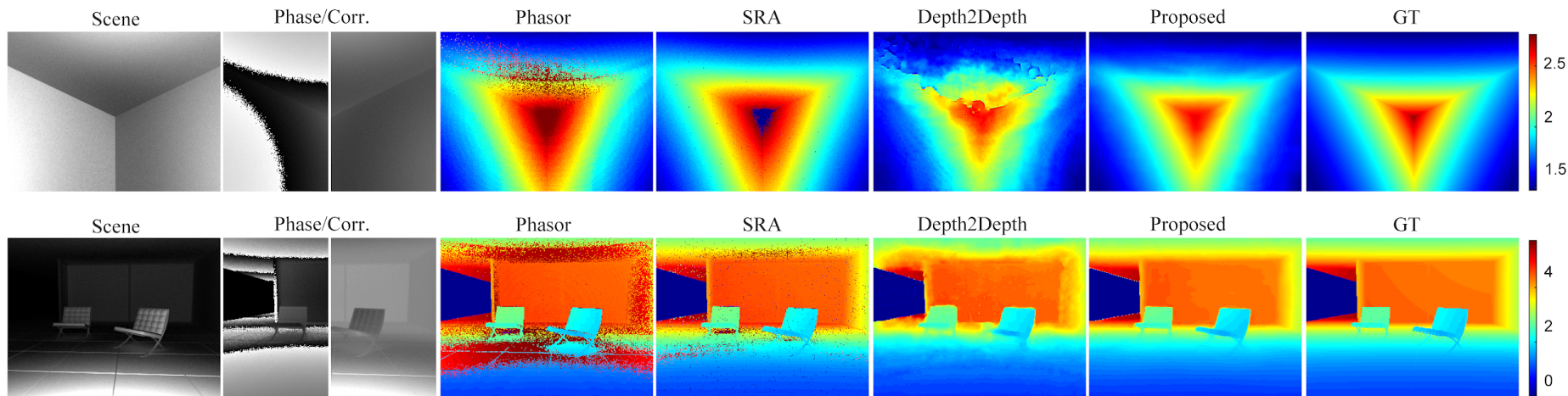
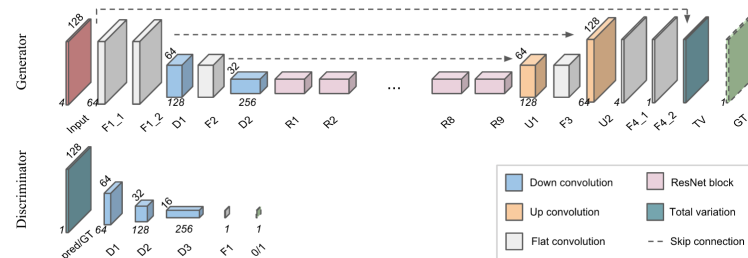
Deep Joint Demosaicking and Denoising



Michaël Gharbi, Gaurav Chaurasia, Sylvain Paris, Frédo Durand. *Deep joint demosaicking and denoising*. ACM Trans. on Graphics (TOG), 2016.

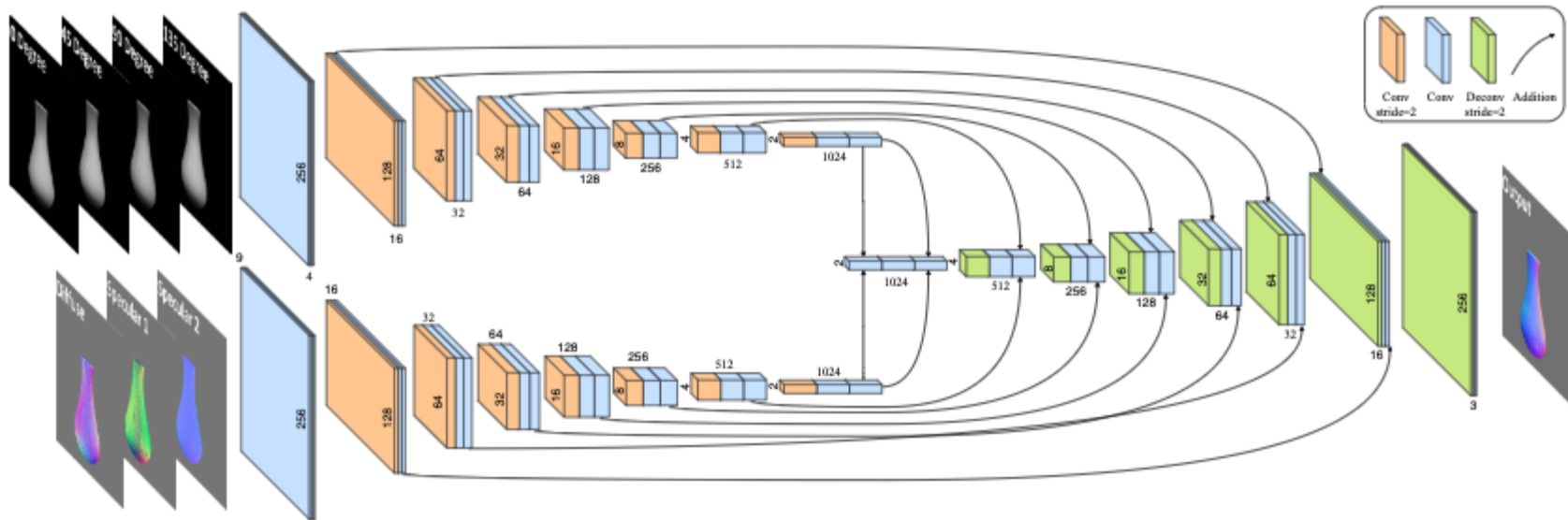
3D Imaging

Deep End-to-End ToF Imaging



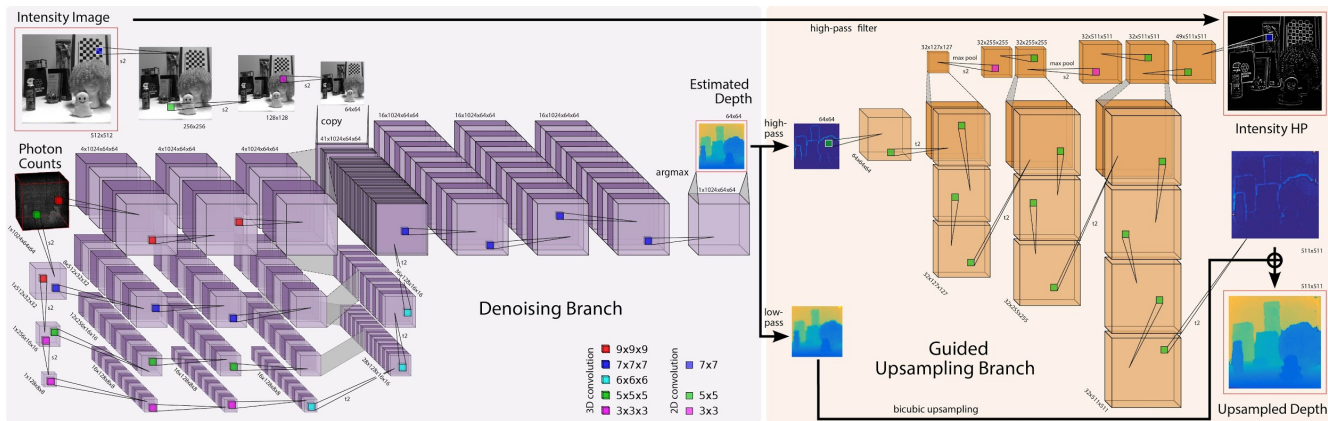
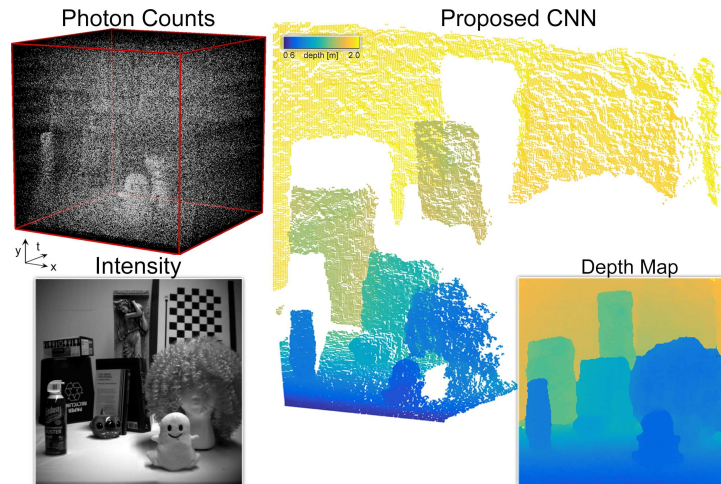
Shuochen Su, Felix Heide, Gordon Wetzstein, Wolfgang Heidrich. *Deep End-to-End ToF Imaging*. CVPR, 2018.

Physics Based Neural Network for Shape from Polarization



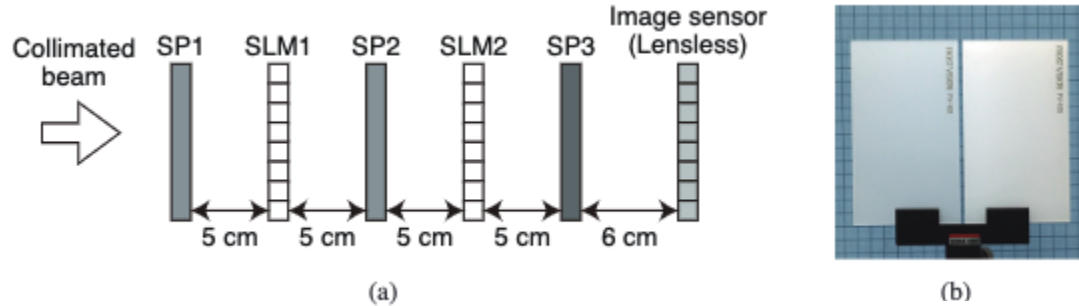
Yunhao Ba, Rui Chen, Yiqin Wang, Lei Yan, Boxin Shi, Achuta Kadambi. *Physics-based Neural Networks for Shape from Polarization*. Arxiv, 2019.

Single Photon 3D Imaging

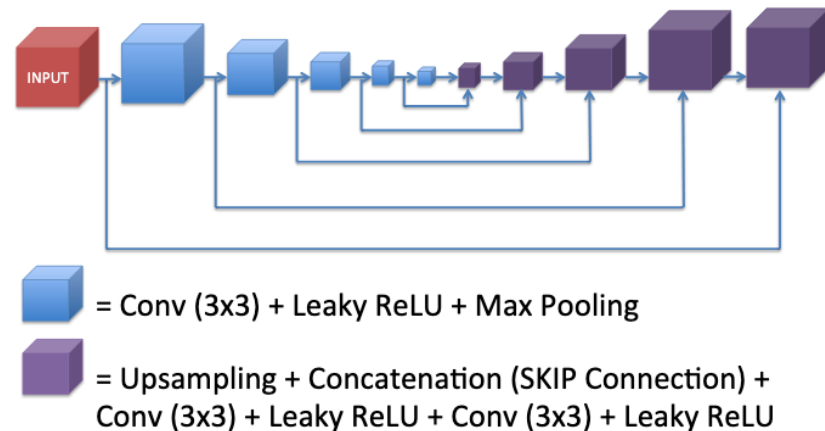


Lensless, Speckle, Scattering

Learning Based Imaging through Scattering Media

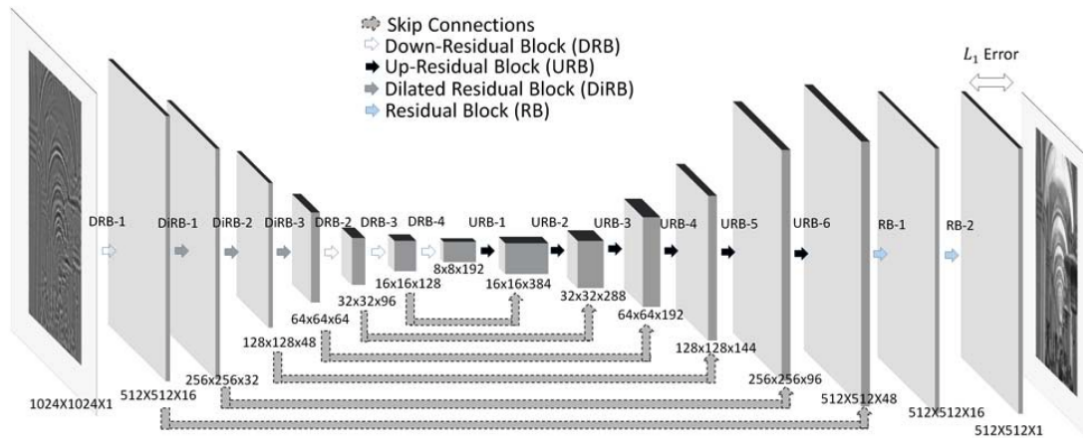
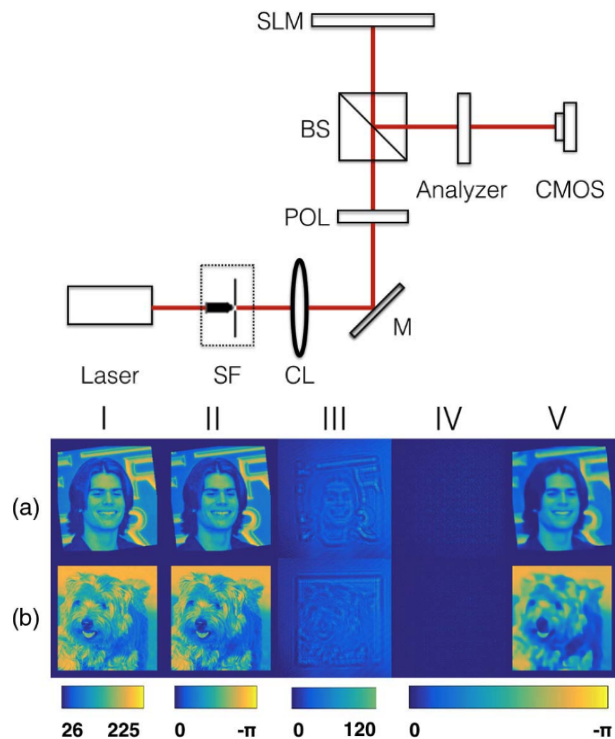


Reconstructing Intensity from Binary Spatial Gradient Cameras

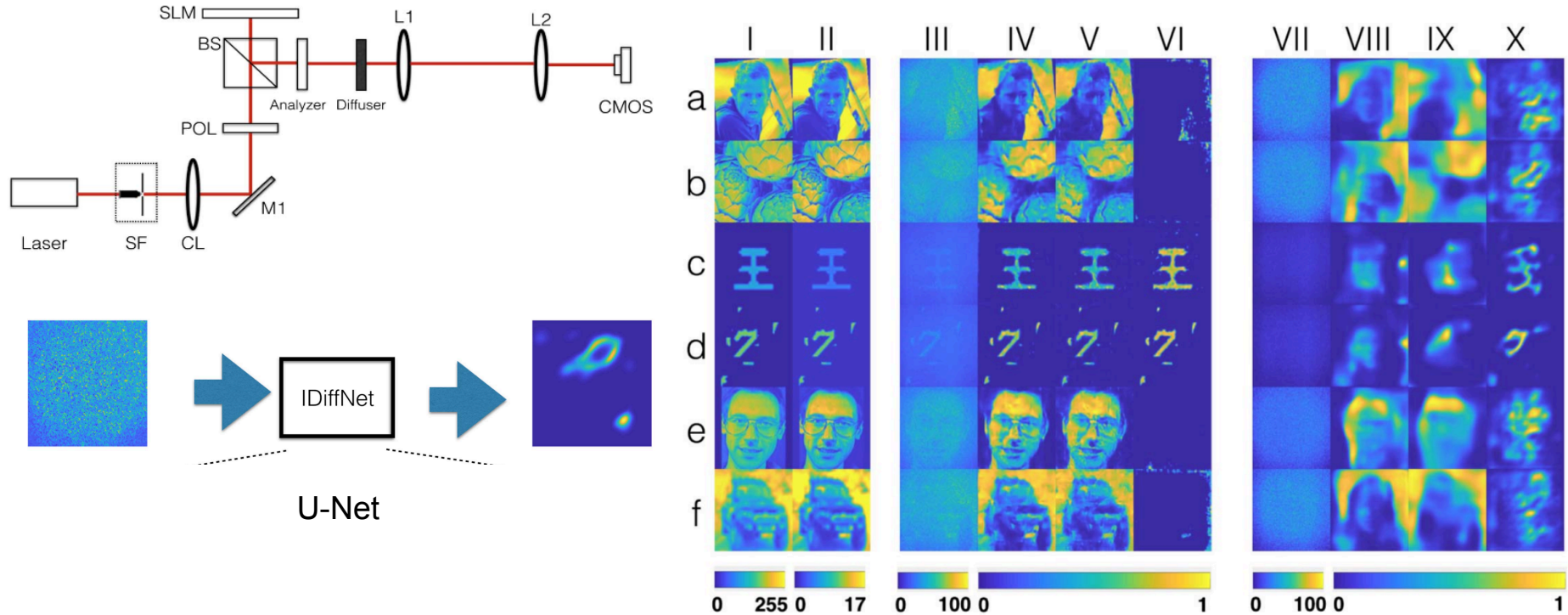


Suren Jayasuriya, Orazio Gallo, Jinwei Gu, Timo Aila, Jan Kautz. *Reconstructing Intensity Images from Binary Spatial Gradient Cameras*. CVPR, 2017.

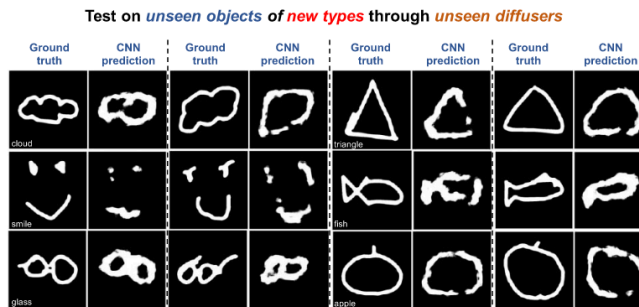
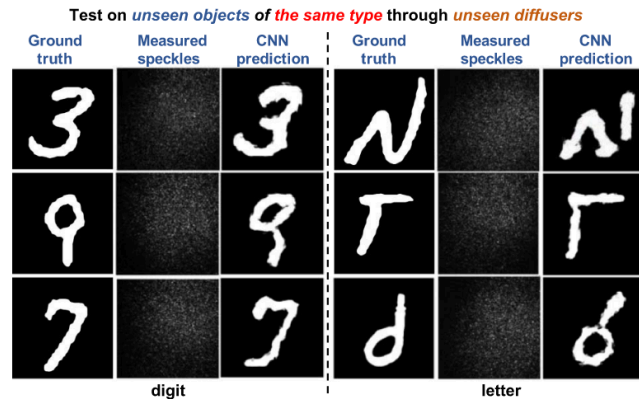
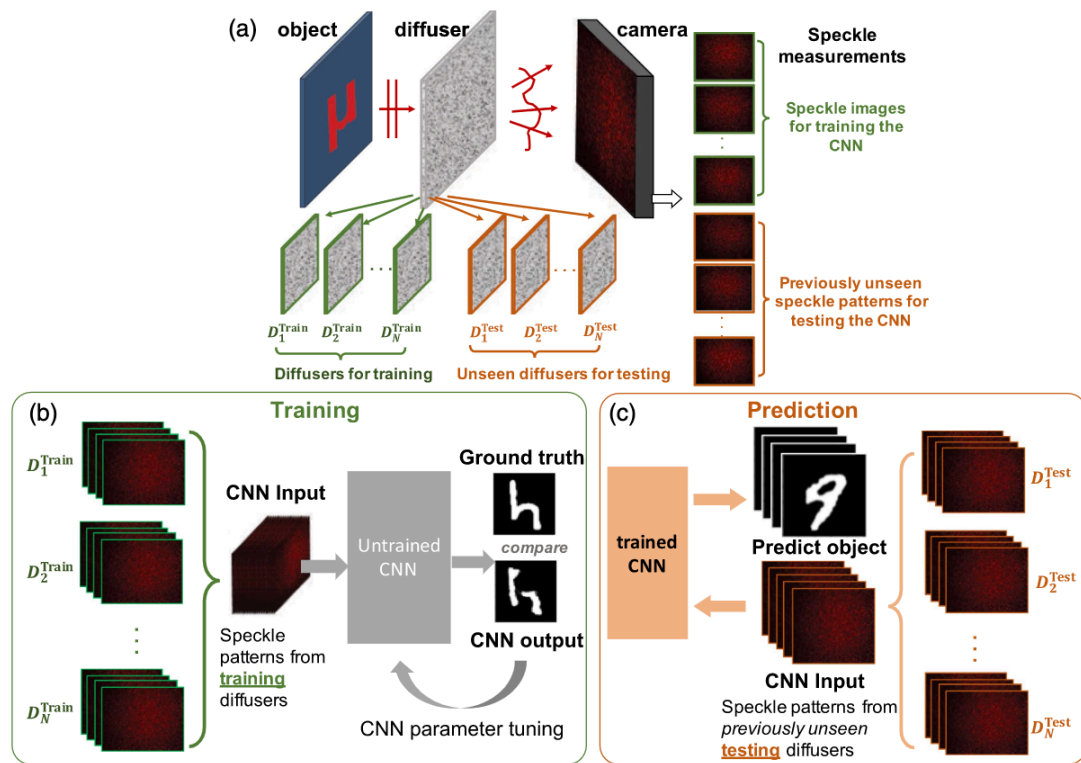
Lensless Computational Imaging through Deep Learning



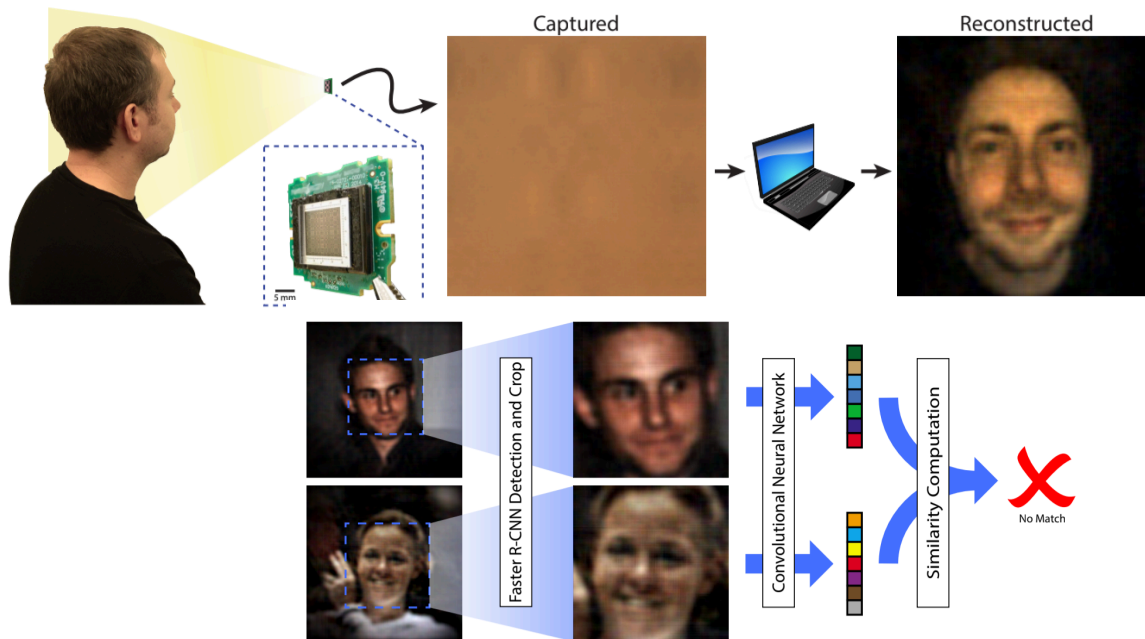
Imaging through glass diffusers using densely connected CNNs



Deep speckle correlation



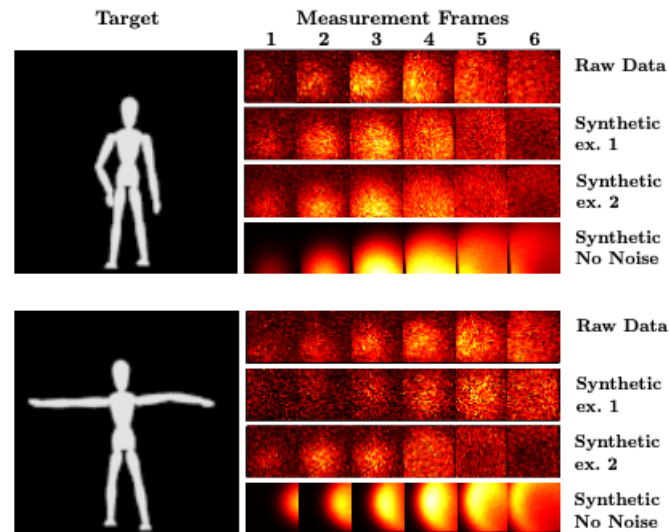
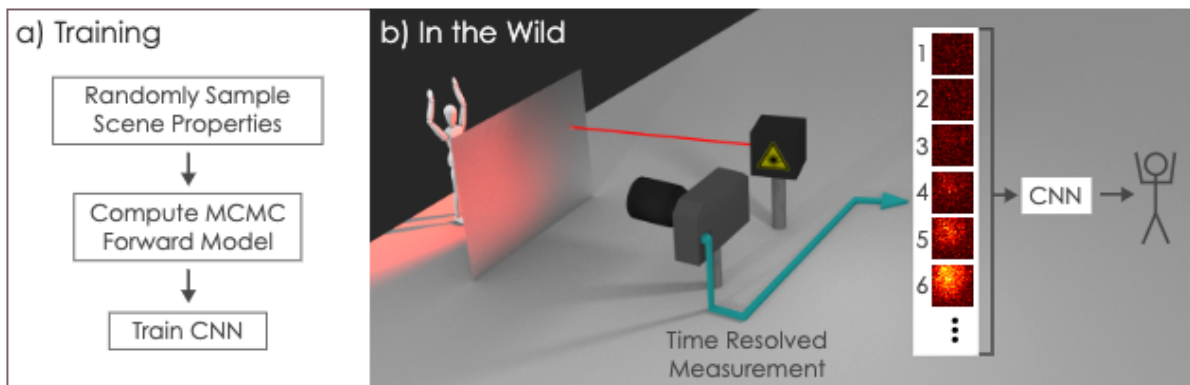
Face Detection and Verification Using Lensless Cameras



J. Tan, L. Niu, J. K. Adams, V. Boominathan, J. T. Robinson, R. G. Baraniuk, and A. Veeraraghavan. *Face Detection and Verification Using Lensless Cameras*. IEEE Trans Comp Imaging, 2018.

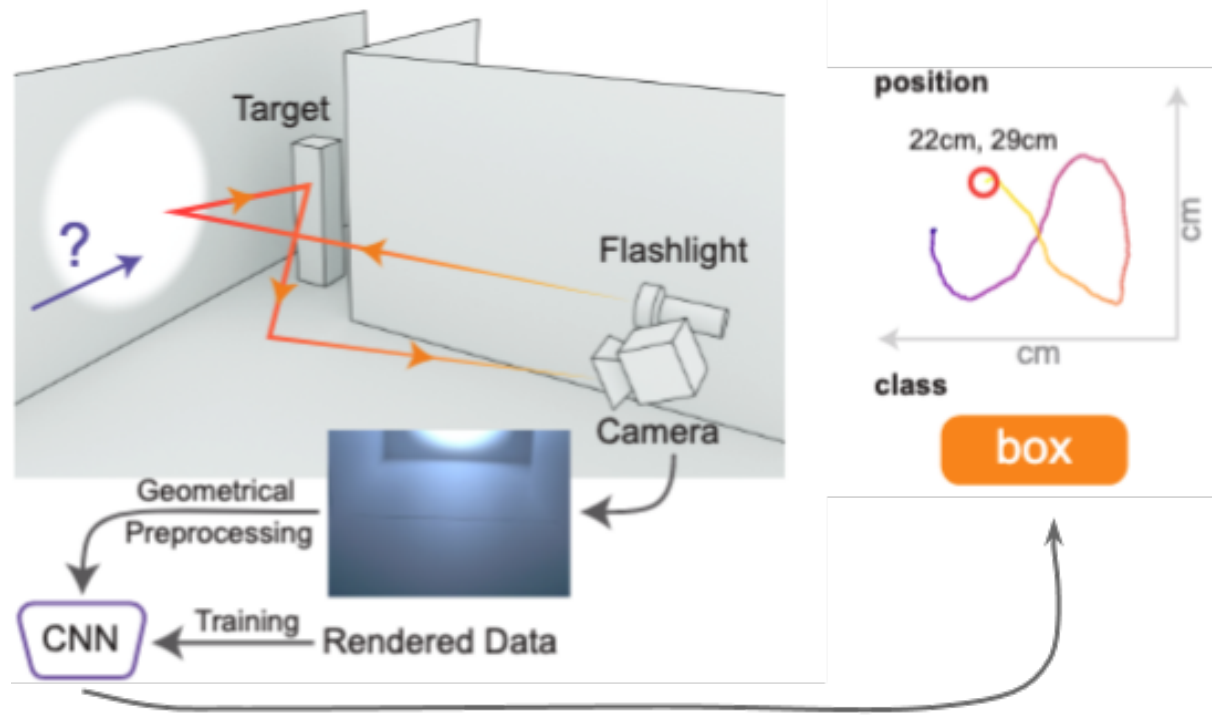
Non-line-of-sight

Classification through Scattering

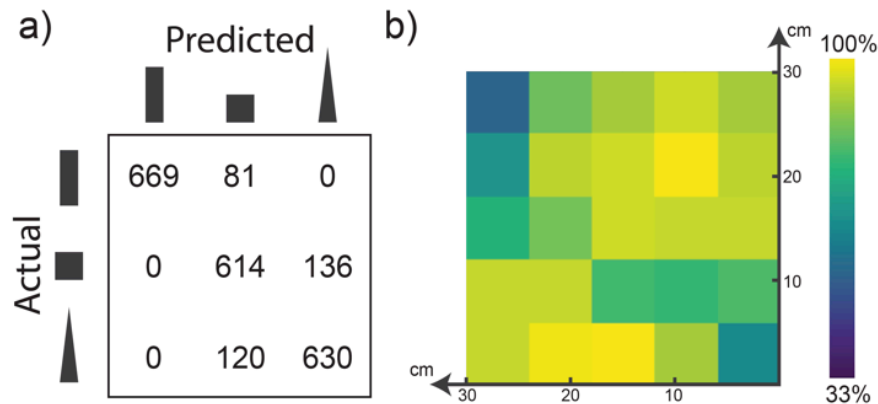


Guy Satat, Matthew Tancik, Otkrist Gupta, Barmak Heshmat, and Ramesh Raskar. *Object classification through scattering media with deep learning on time resolved measurement*. Optics Express, 2017.

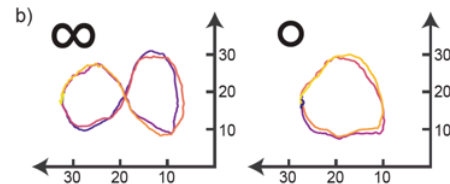
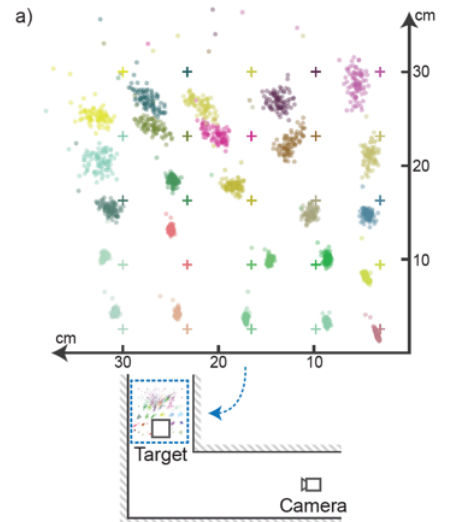
Flash Photography for Data-driven Hidden Scene Recovery



Flash Photography for Data-driven Hidden Scene Recovery

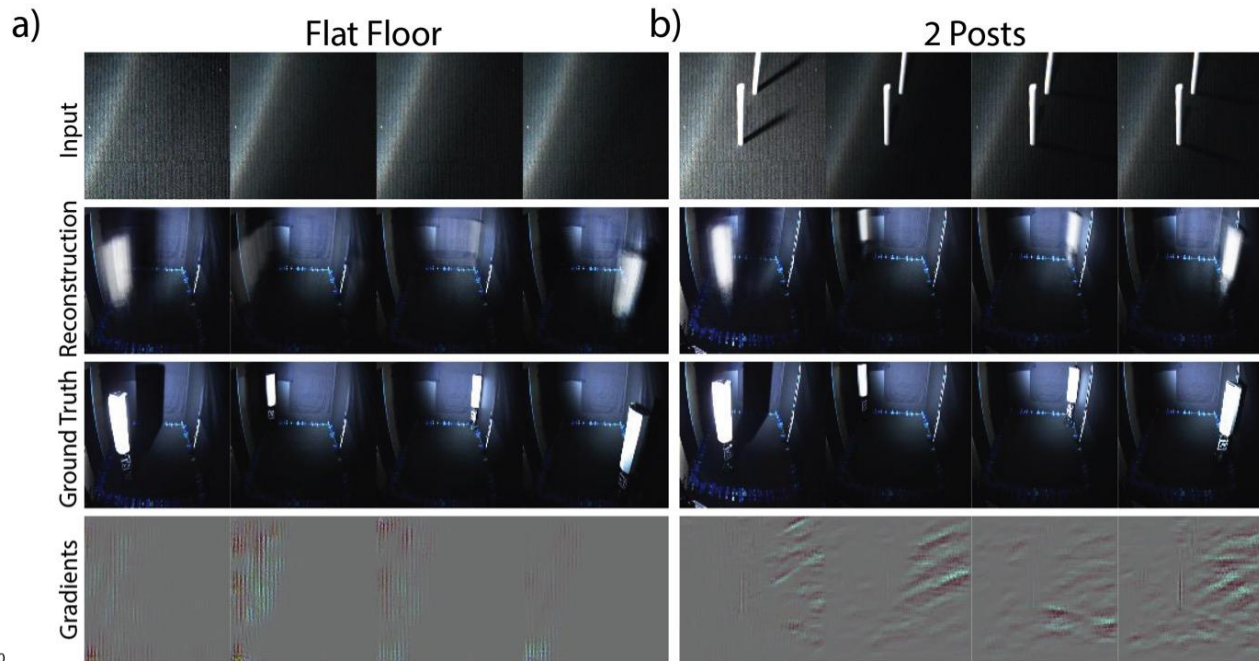
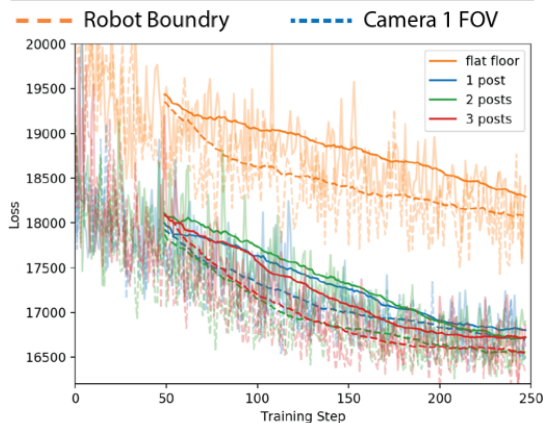
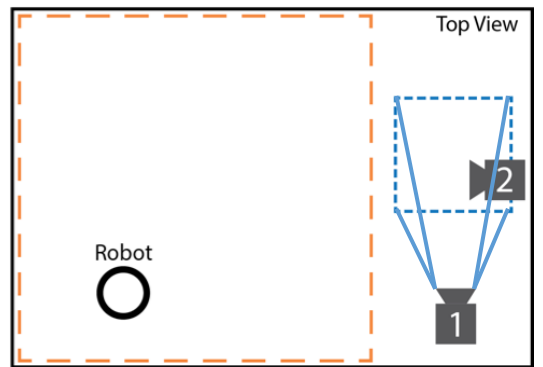


Classification

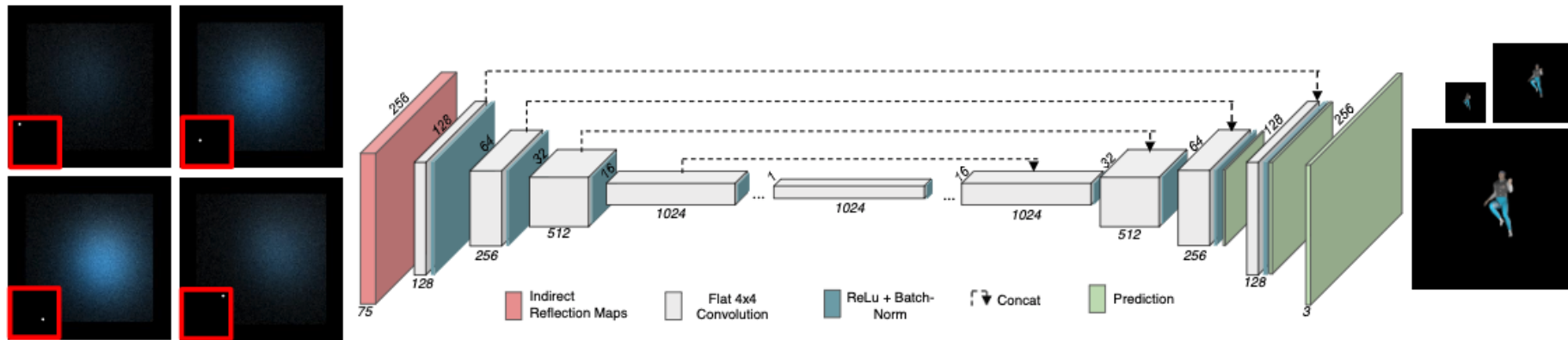


Localization

Data Driven NLOS with a Traditional Camera



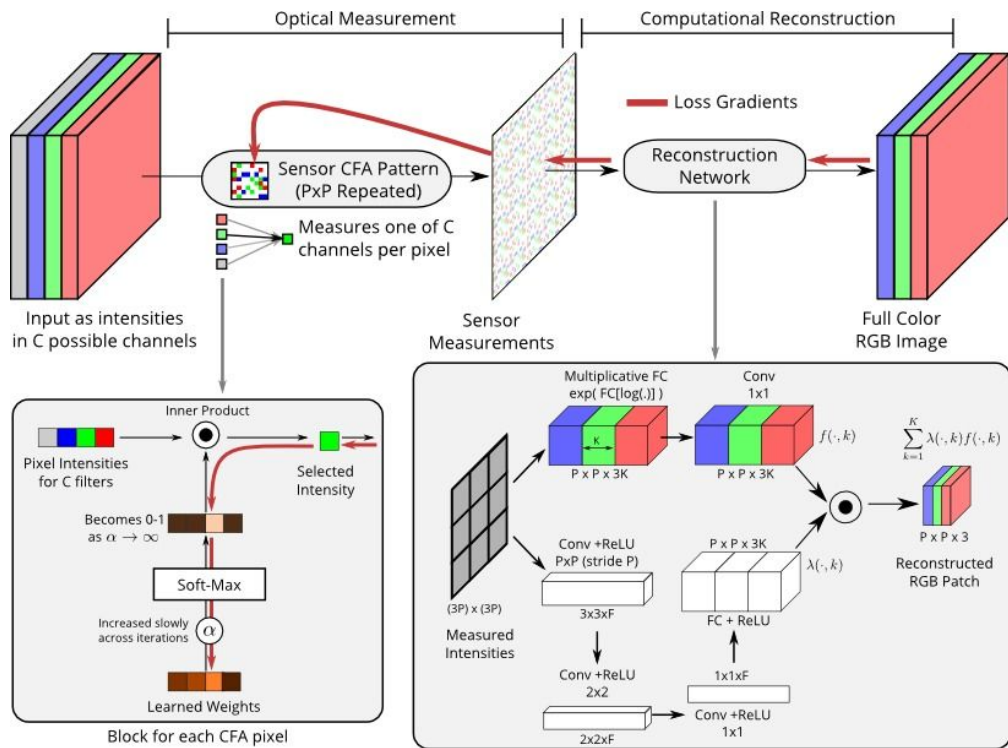
Steady State NLOS



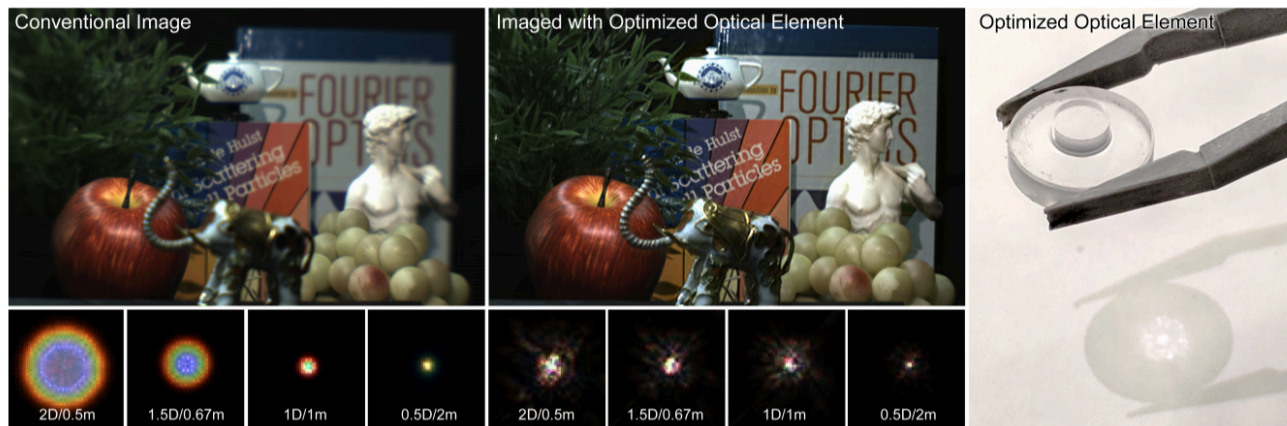
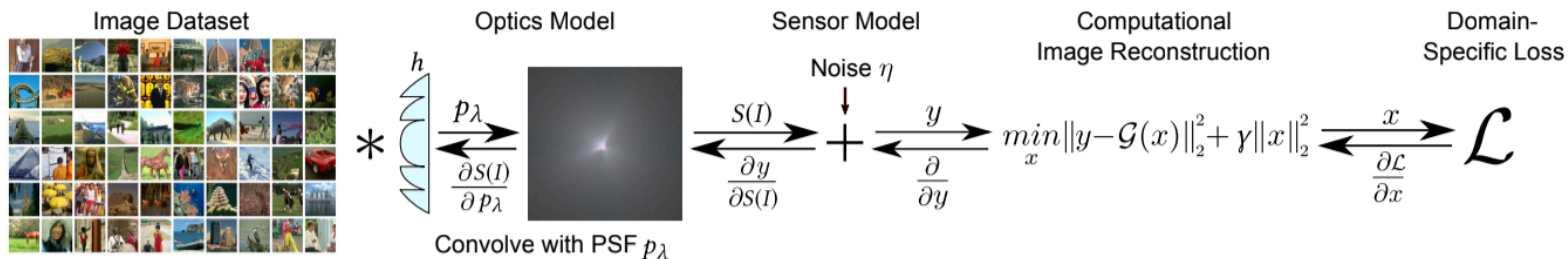
Wenzheng Chen, Simon Daneau, Fahim Mannan, Felix Heide. *Steady-state Non-Line-of-Sight Imaging*. CVPR, 2019.

Imaging System Design

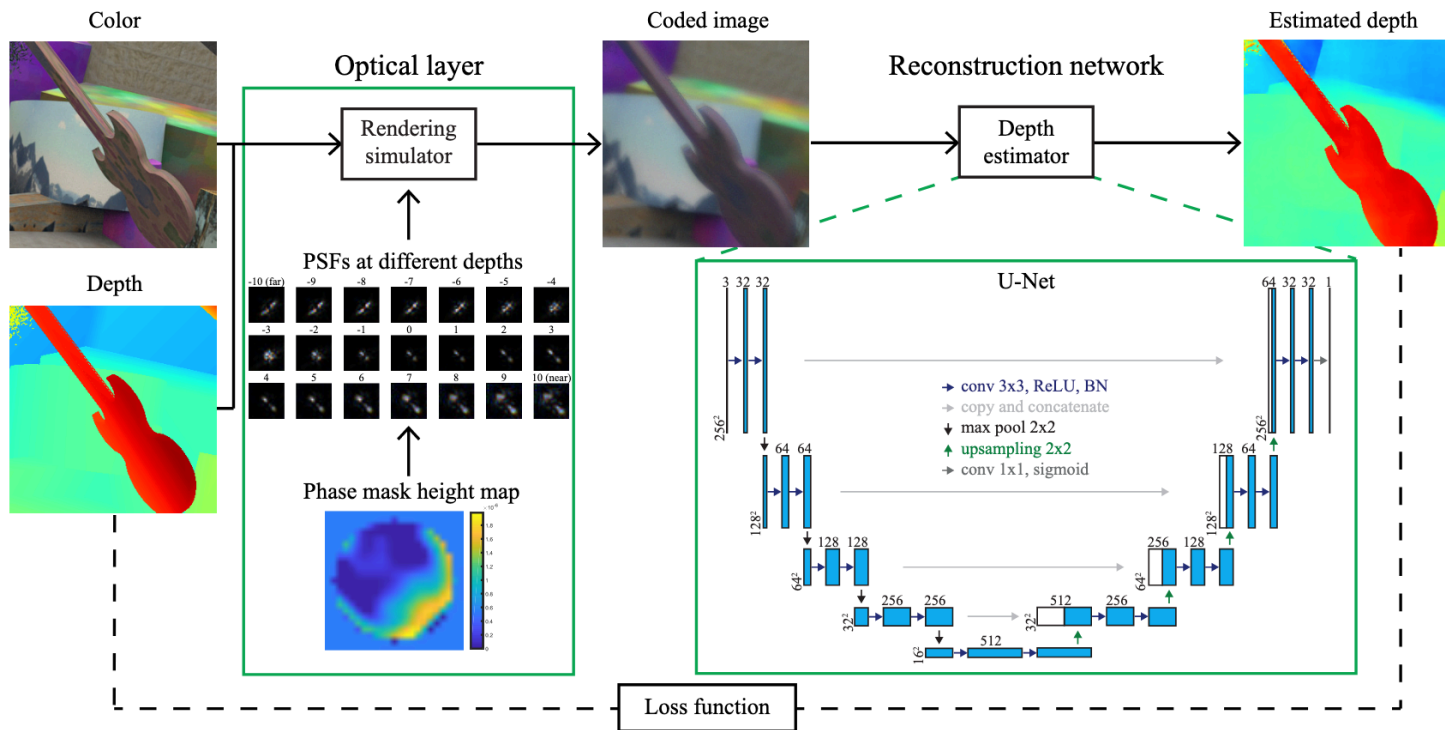
Learning Sensor Multiplexing Design through Back-propagation



Achromatic Extended Depth of Field and Super-resolution Imaging

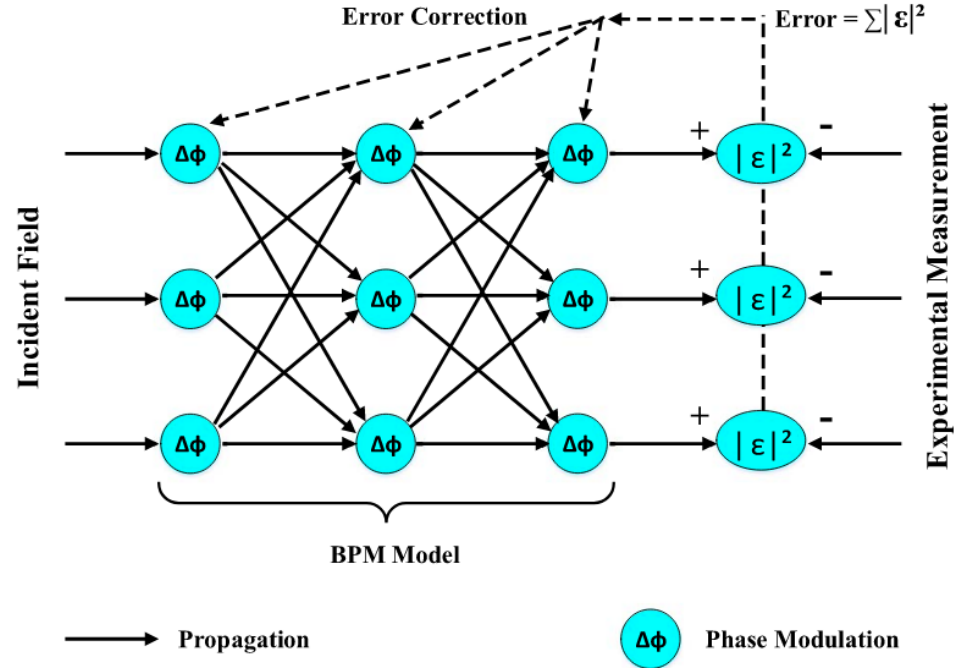
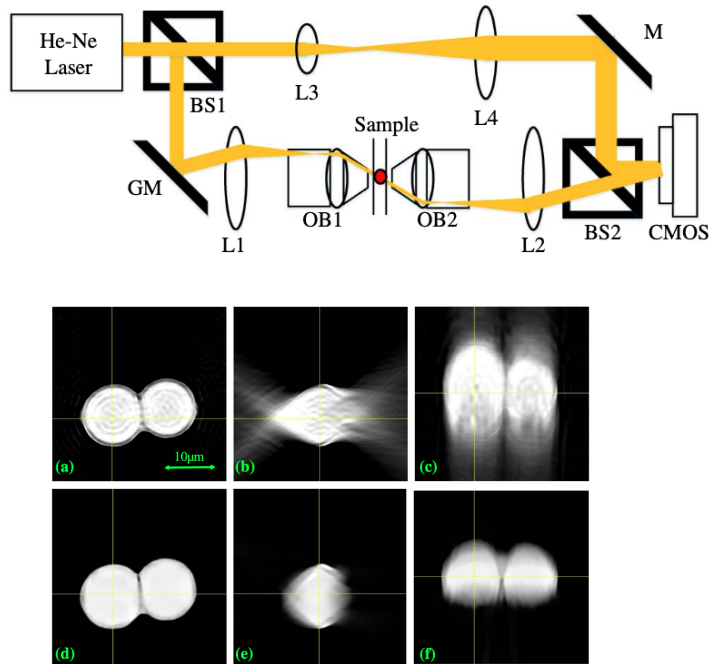


PhaseCam3D

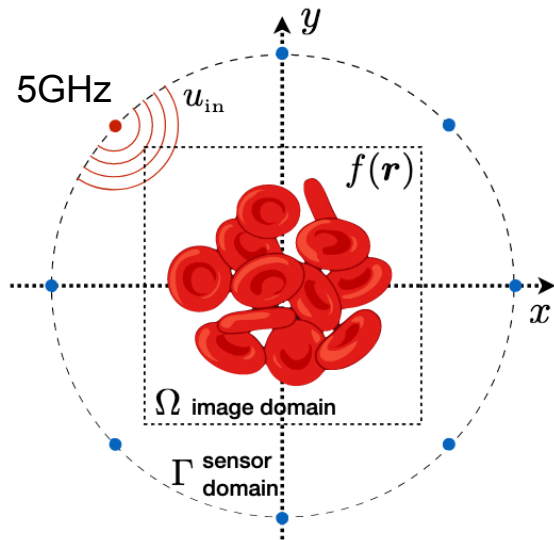


Tomography and Deconvolution

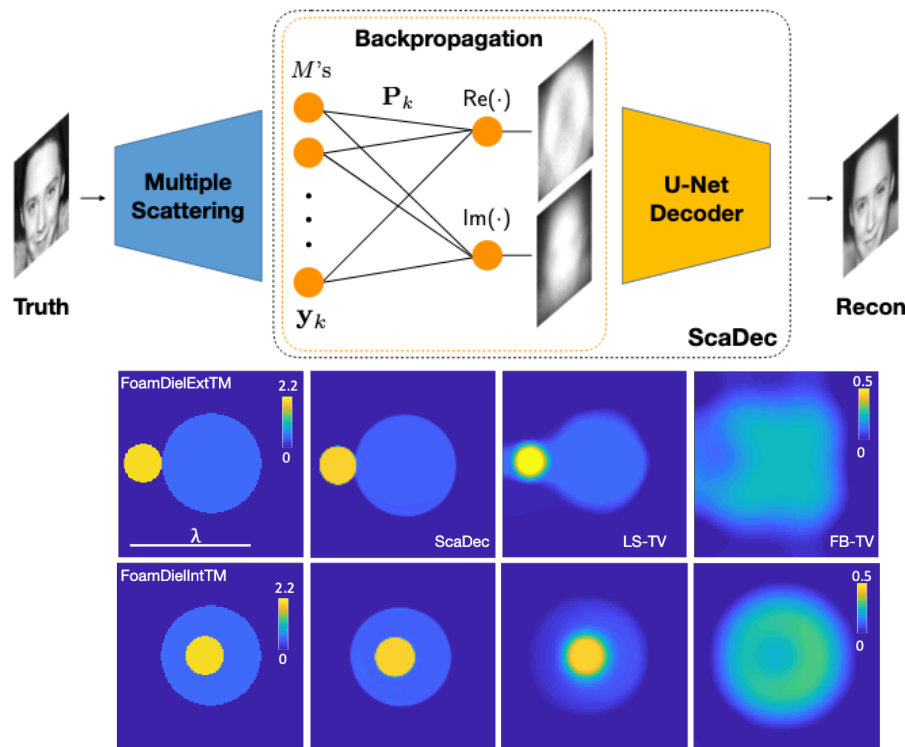
Learning Approach to Optical Tomography



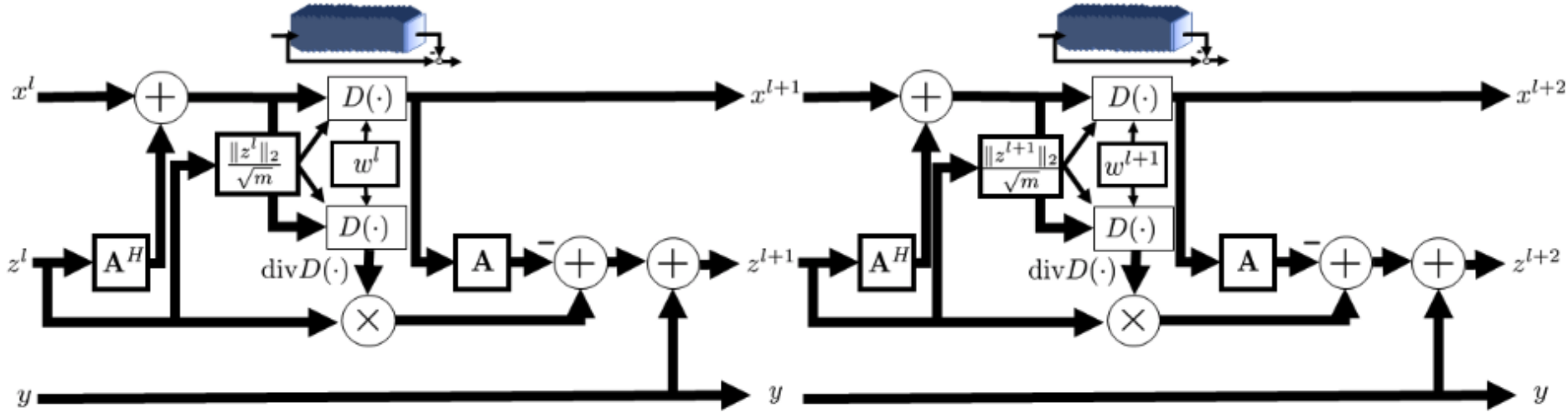
Efficient and accurate inversion of multiple scattering with deep learning



$$\hat{\mathbf{x}} = \arg \min_{\mathbf{x} \in \mathbb{R}^N} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{H}(\mathbf{x})\|_{\ell_2}^2 + \mathcal{R}(\mathbf{x}) \right\}$$

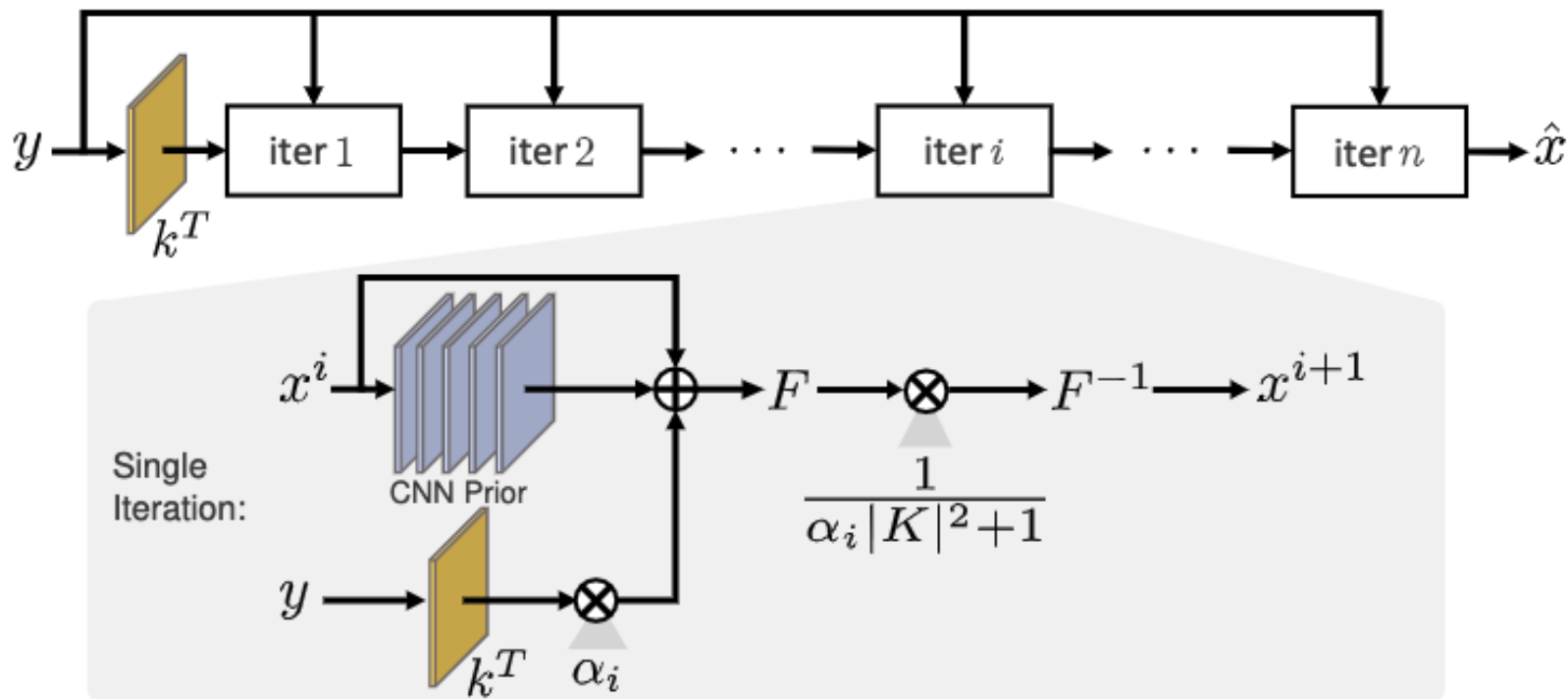


Unrolled Optimization: Learned D-AMP

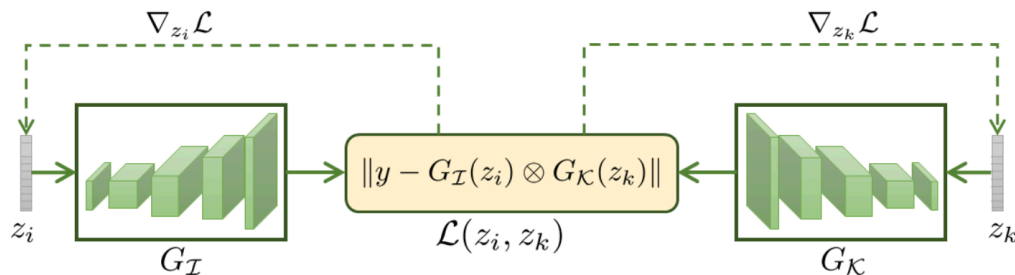


C. A. Metzler, A. Mousavi, R. G. Baraniuk, *Learned D-AMP: Principled Neural Network based Compressive Image Recovery*. NIPS, 2017.

Unrolled Optimization: Deep Priors



Blind Image Deconvolution using Deep Generative Priors



$$\begin{aligned} \underset{i, z_i, z_k}{\operatorname{argmin}} \quad & \|y - i \otimes G_K(z_k)\|^2 + \tau \|i - G_I(z_i)\|^2 \\ & + \zeta \|y - G_I(z_i) \otimes G_K(z_k)\|^2 + \rho \|i\|_{\text{tv}}. \end{aligned}$$

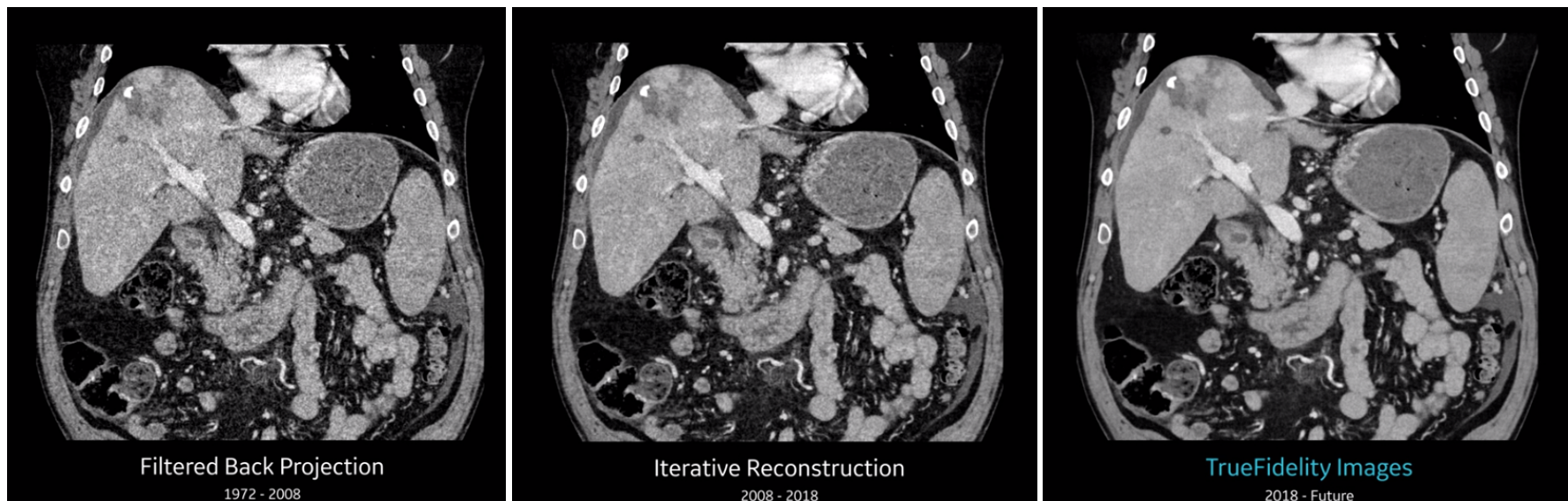


M. Asim, F. Shamshad, A. Ahmed. *Blind Image Deconvolution using Deep Generative Priors*. Arxiv, 2019.

See Also: Paul Hand and Vladislav Voroninski. *Global Guarantees for Enforcing Deep Generative Priors by Empirical Risk*. Proceedings of Conf. On Learning Theory, PMLR, 2018.

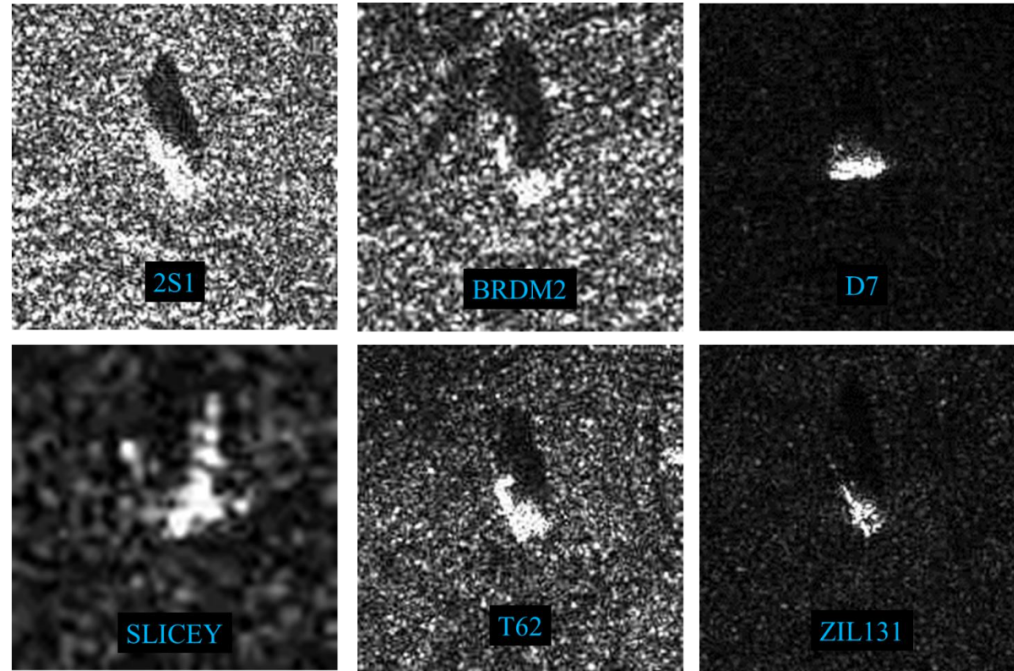
GE APEX CT

Deep Learning Image Reconstruction: Cleared by FDA in April 2019



<https://www.gehealthcare.com/en-GB/products/computed-tomography/revolution-apex>

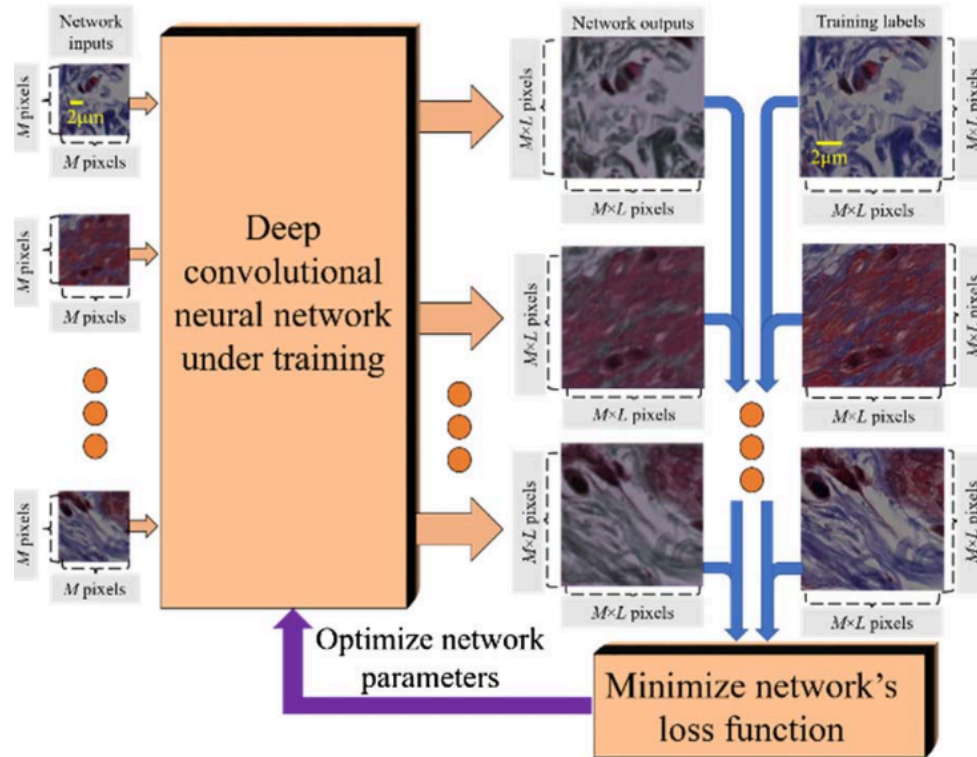
Convolutional neural networks for synthetic aperture radar classification



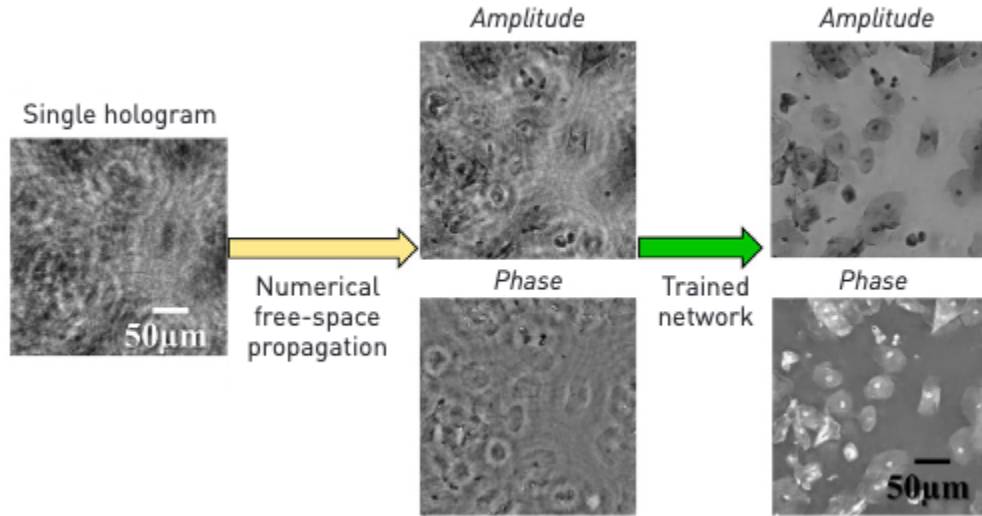
Andrew Profeta, Andres Rodriguez, H. Scott Clouse. *Convolutional neural networks for synthetic aperture radar classification*. Proc. SPIE 9843, Algorithms for Synthetic Aperture Radar Imagery XXIII, 2016.

Microscopy

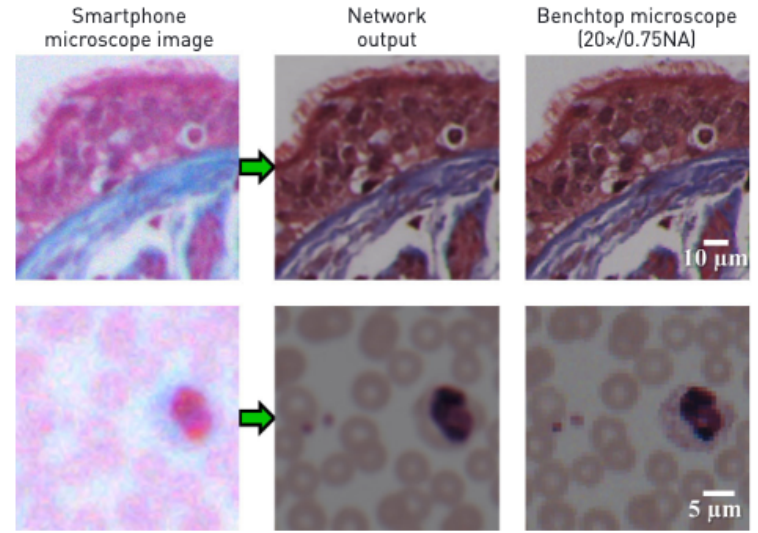
Deep learning microscopy



Towards a Thinking Microscope



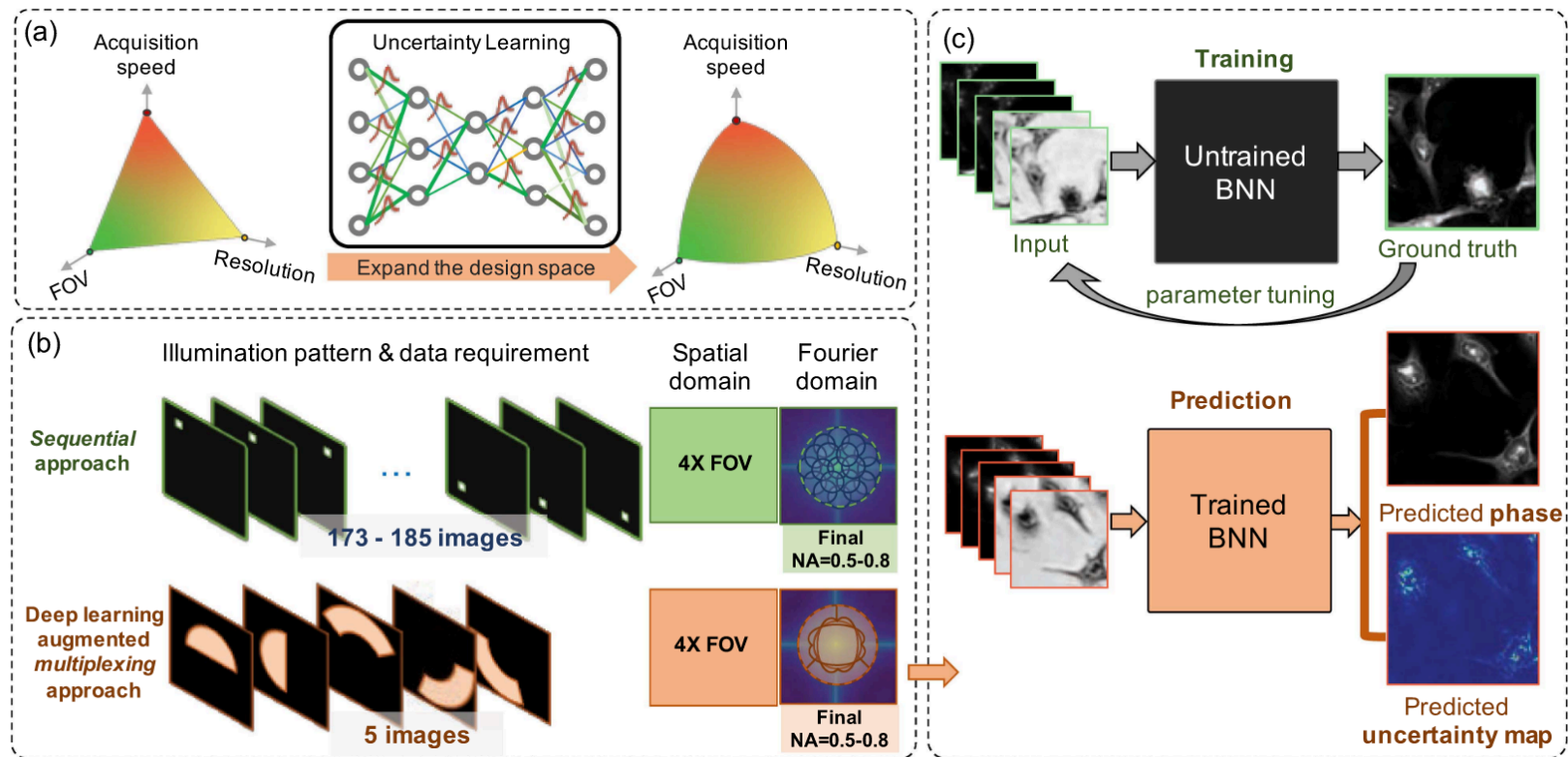
(a)



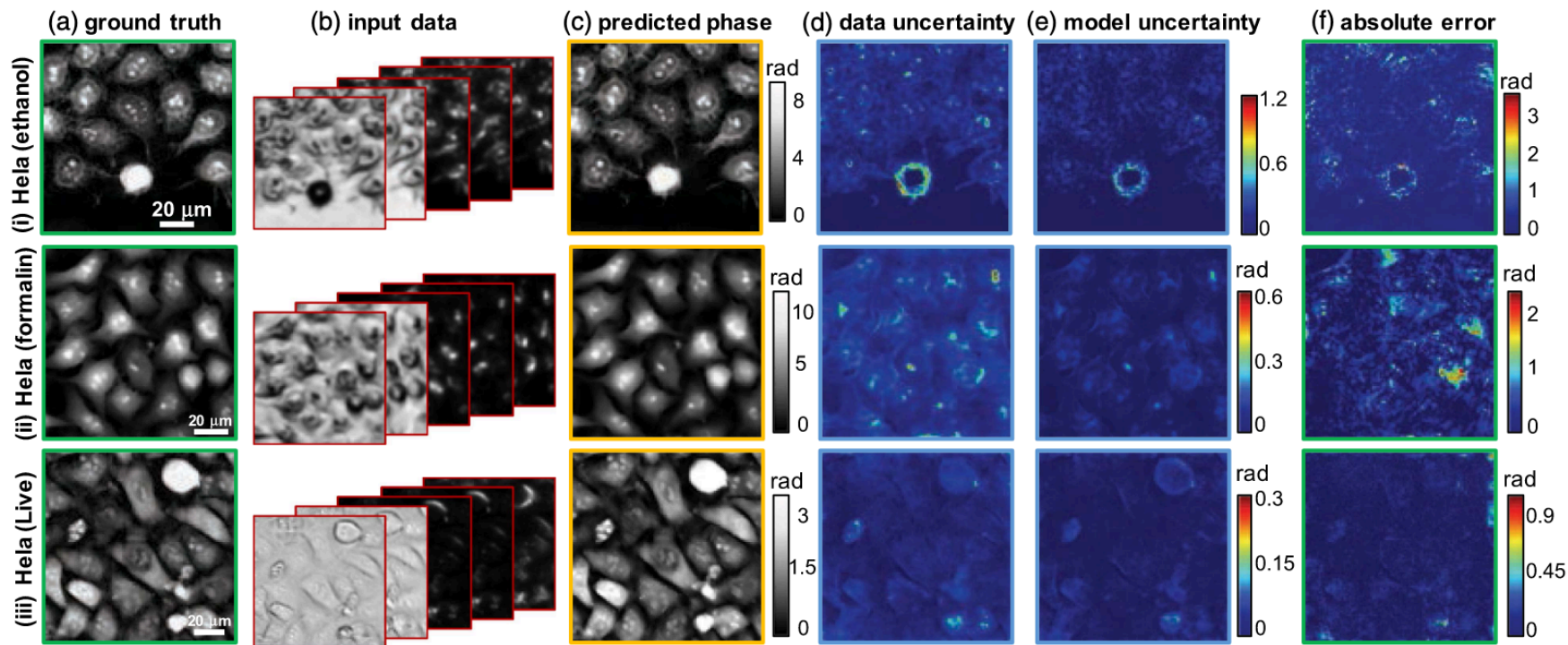
(b)

Y. Rivenson and A. Ozcan. *Toward a Thinking Microscope: Deep Learning in Optical Microscopy and Image Reconstruction*. OSA OPN , 2018.

Reliable deep-learning-based phase imaging with uncertainty quantification



Reliable deep-learning-based phase imaging with uncertainty quantification



Summary

- Moving beyond pure classification problems
- U-net is very popular architecture
- “Hybrid” iterative methods using learning is an emerging field
- Still difficult to demonstrate generalization across different optical setups
 - Calibration to synthetic training data still required
 - Training data collected on same instrument as test device

Summary

Computational Imaging is Diverse:

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- 3D Imaging
- **Lensless, Speckle, Scattering**
- **Non-line-of-sight**
- **Imaging System Design**
- Tomography and Deconvolution
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